

# Microeconomics Theory I

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(TelAS)

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# Introduction & Objectives

The course covers:

- Decision theoretic models of choice: with and without uncertainty
- Classical theories of consumer and producer behavior
- Classical theories of markets and the competitive equilibrium

The objective of the course is to provide students with a firm grounding in the analytic methods of microeconomics theory.

Although the course is centered around classical theories of economic behavior, new developments in these fields will also be discussed.

# General Information

**Email:** sepehrekbatani@teias.institute

**Lectures:** Sat, Mon 11AM-12:30PM

**Office Hours:** Sat 3-4PM

## **Textbooks:**

- Riley, Essential Microeconomics, Cambridge University Press, 2012
- [Supplementary] Mas-Colell, Whinston, Green, Microeconomics Theory, Oxford University Press, 1995.

# Course Outline

- 1 Introduction and Maximization:  
*Riley, Chapter 1*
- 2 Decision Theory & Consumer Theory:  
*Riley, Chapter 2*
- 3 Producer Theory:  
*Riley, Chapter 4*
- 4 Markets and Equilibrium:  
*Riley, Chapters 3 and 5*
- 5 Choice under Uncertainty:  
*Riley, Chapter 7*
- 6 Externalities and Public Goods:  
*MWG, Chapter 11*
- 7 Equilibrium in Financial Markets:  
*Riley, Chapter 8*

# Teaching Assistants

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  - OH: Tue 9:30-10:30 AM

## Section 1

# Maximization

# Example 1 - Profit Maximizing Firm

Cost Function:  $C(q) = 5 + 12q + 3q^2$

Demand price function:  $p(q) = 20 - q$

Solve for the profit maximizing output and price?

## Example 2 - Two Products

### Model 1

Cost function:  $C(q) = 10q_1 + 15q_2 + 2q_1^2 + 3q_1q_2 + 2q_2^2$

Demand price function:  $p_1 = 85 - \frac{1}{4}q_1$  and  $p_2 = 90 - \frac{1}{4}q_2$

Solve for the profit maximizing outputs?

### Model 2

Cost function:  $C(q) = 10q_1 + 15q_2 + q_1^2 + 3q_1q_2 + q_2^2$

Demand price function:  $p_1 = 65 - \frac{1}{4}q_1$  and  $p_2 = 70 - \frac{1}{4}q_2$

Solve for the profit maximizing outputs?



# Model 1

**Revenue:**

$$R_1 = p_1 q_1 = \left(85 - \frac{1}{4}q_1\right)q_1 = 85q_1 - \frac{1}{4}q_1^2$$

$$R_2 = p_2 q_2 = \left(90 - \frac{1}{4}q_2\right)q_2 = 90q_2 - \frac{1}{4}q_2^2$$

**Profit:**

$$\begin{aligned}\pi &= R_1 + R_2 - C \\ &= 85q_1 - \frac{1}{4}q_1^2 + 90q_2 - \frac{1}{4}q_2^2 - (10q_1 + 15q_2 + 2q_1^2 + 3q_1q_2 + 2q_2^2) \\ &= 75q_1 + 75q_2 - \frac{9}{4}q_1^2 - \frac{9}{4}q_2^2 - 3q_1q_2\end{aligned}$$

# Think on the Margin

Marginal profit of increasing  $q_1$ :

$$\frac{\partial \pi}{\partial q_1} = 75 - \frac{9}{2}q_1 - 3q_2.$$

Therefore the profit maximizing choice is:

$$q_1 = m_1(q_2) = \frac{2}{9}(75 - 3q_2) = \frac{2}{3}(25 - q_2)$$

Marginal profit of increasing  $q_2$ :

$$\frac{\partial \pi}{\partial q_2} = 75 - 3q_1 - \frac{9}{2}q_2.$$

Therefore the profit maximizing choice is:

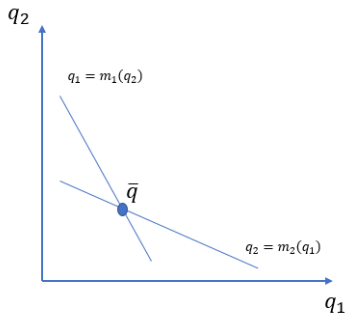
$$q_2 = m_2(q_1) = \frac{2}{9}(75 - 3q_1) = \frac{2}{3}(25 - q_1)$$

# Profit Maximizing Outputs

$$q_1 = m_1(q_2) = \frac{2}{3}(25 - q_2), \quad q_2 = m_2(q_1) = \frac{2}{3}(25 - q_1)$$

If you solve for  $q$  satisfying both equations you will find that the unique solution is:

$$\bar{q} = (\bar{q}_1, \bar{q}_2) = (10, 10)$$



## Model 2

**Cost function:**  $C(q) = 10q_1 + 15q_2 + q_1^2 + 3q_1q_2 + q_2^2$

**Demand functions:**  $p_1 = 65 - \frac{1}{4}q_1$  and  $p_2 = 70 - \frac{1}{4}q_2$

**Revenue:**

$$R_1 = p_1 q_1 = (65 - \frac{1}{4}q_1)q_1 = 65q_1 - \frac{1}{4}q_1^2$$

$$R_2 = p_2 q_2 = (70 - \frac{1}{4}q_2)q_2 = 70q_2 - \frac{1}{4}q_2^2$$

**Profit:**

$$\begin{aligned}\pi &= R_1 + R_2 - C \\ &= 55q_1 + 55q_2 - \frac{5}{4}q_1^2 - \frac{5}{4}q_2^2 - 3q_1q_2\end{aligned}$$

# Think on the Margin

Marginal profit of increasing  $q_1$ :

$$\frac{\partial \pi}{\partial q_1} = 55 - \frac{5}{2}q_1 - 3q_2.$$

Therefore for any  $q_2$  profit maximizing  $q_1$  is:

$$q_1 = m_1(q_2) = \frac{2}{5}(55 - 3q_2)$$

Marginal profit of increasing  $q_2$ :

$$\frac{\partial \pi}{\partial q_2} = 55 - 3q_1 - \frac{5}{2}q_2.$$

Therefore for any  $q_1$  profit maximizing  $q_2$  is:

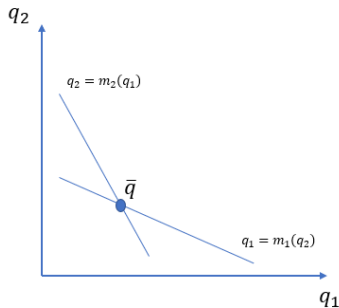
$$q_2 = m_2(q_1) = \frac{2}{5}(55 - 3q_1)$$

# Profit Maximizing Outputs

$$q_1 = m_1(q_2) = \frac{2}{5}(55 - 3q_2), \quad q_2 = m_2(q_1) = \frac{2}{5}(55 - 3q_1)$$

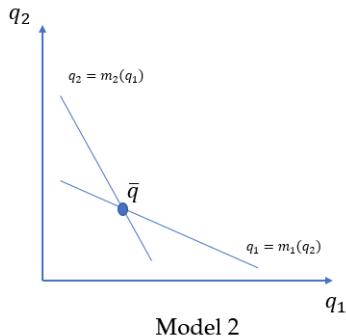
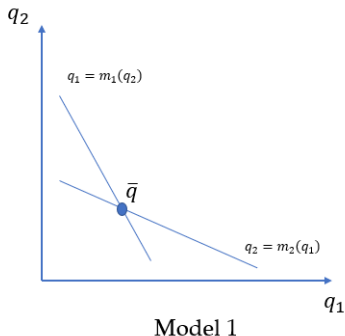
If you solve for  $\bar{q}$  satisfying both equations you will find that the unique solution is:

$$\bar{q} = (\bar{q}_1, \bar{q}_2) = (10, 10)$$



# Comparison Between Two Models

These look very similar to the profit-maximizing lines in Model 1. However, now the profit-maximizing line for  $q_2$  is steeper (i.e. has a more negative slope).



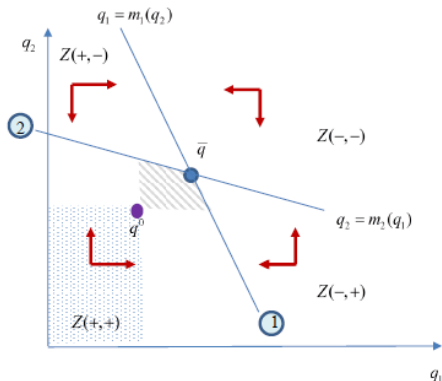
As we shall see this makes a critical difference.

# Model 1 Analysis

Is  $\bar{q} = (\bar{q}_1, \bar{q}_2)$  the profit maximizing output?

The arrows indicate the directions in which  $\pi(q_1, q_2)$  increases.

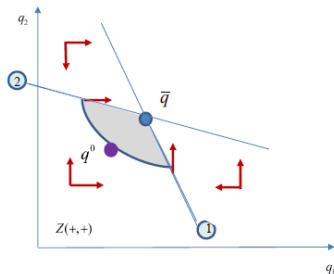
Consider the point  $q^0$ . Profit is higher in the shaded region and lower in the dotted region. The level set through  $q^0$  must have a negative slope.





# Model 1 Analysis Cont.

The level set  $\pi(q) = \pi(q^0)$  in the  $Z(+, +)$  region.

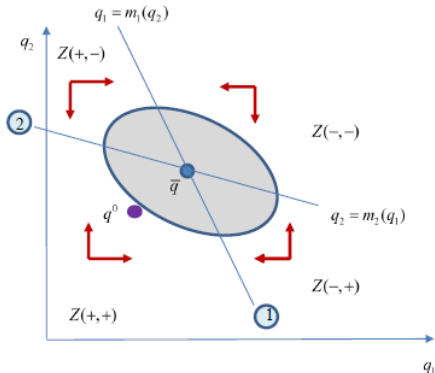


Profit is higher in the shaded region.

Note that the level set is parallel to the  $q_2$  axis at the point of intersection with the maximizing line for  $q_2$  and is parallel to the horizontal axis at the point of intersection with the maximizing line for  $q_1$ .

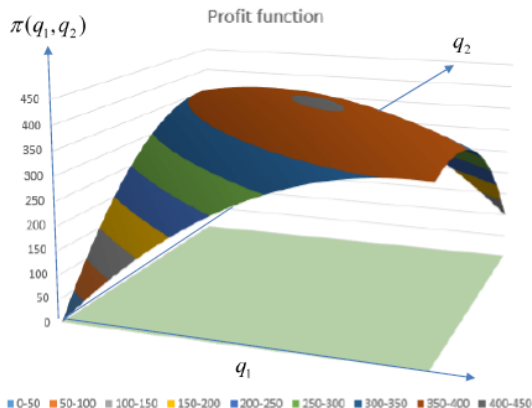
# Model 1 Analysis Cont.

The level set  $\pi(q) = \pi(q^0)$  and superlevel set  $\pi(q) \geq \pi(q^0)$ :



# Model 1 Analysis Cont.

The profit,  $\pi(q_1, q_2)$  is depicted below:

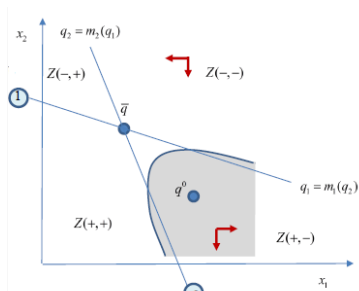


# Model 2 Analysis

There are four Zones:

- $Z(+, +)$ : The zone in which profit is increasing in  $q_1$  and  $q_2$ .
- $Z(+, -)$ : The zone in which profit is increasing in  $q_1$  and decreasing in  $q_2$ .
- ...

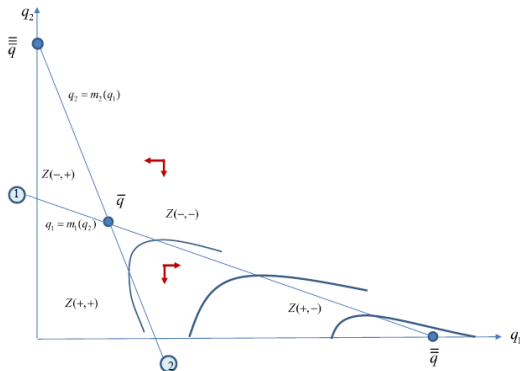
**Never** leads to the intersection point  $\bar{q} = (10, 10)$



# Model 2 Analysis Cont.

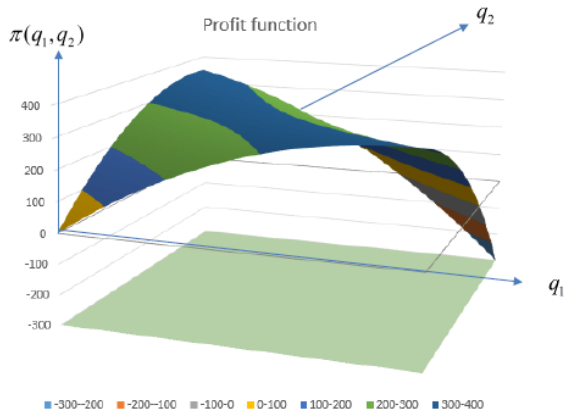
Local Maximum  $\bar{q} = (\bar{q}_1, 0)$  on the  $q_1$  axis.

By an essentially identical argument, there is a second local maximum  $\bar{\bar{q}}$  on the  $q_2$  axis.



# Model 2 Analysis Cont.

The profit function has the shape of a saddle. The output vector  $\bar{q}$  where the slope in the direction of each axis is zero is called a saddle-point.



# Interior and Boundary Solution

Model 1 has an **Interior Solution**.

Model 2 has two **Boundary Solutions**.

When solving for such an example, remember to check for both types of solutions and compare the value of the function you are maximizing.

# First Order Condition

Consider the two variable problem:

$$\max_{q} f(q_1, q_2)$$

## First Order Necessary Conditions for a Maximum

For  $\bar{q} \gg 0$  to be a maximizer, the following two conditions must hold:

$$\frac{\partial f}{\partial q_1}(\bar{q}) = 0 \quad \text{and} \quad \frac{\partial f}{\partial q_2}(\bar{q}) = 0$$



# Second Order Condition

Suppose that the first order necessary conditions hold at  $\bar{q}$ . A necessary condition for a maximum is that the slope must be decreasing.

## Second Order Necessary Conditions for a Maximum

For  $\bar{q} \gg 0$  to be a maximizer, the following two conditions must hold:

$$\frac{\partial}{\partial q_1} \frac{\partial f}{\partial q_1}(\bar{q}_1, \bar{q}_2) \leq 0 \quad \text{and} \quad \frac{\partial}{\partial q_2} \frac{\partial f}{\partial q_2}(\bar{q}_1, \bar{q}_2) \leq 0$$

# Sufficient Conditions

As we have seen, these conditions are necessary for a maximum, by they **don't** guarantee that  $\bar{q}$  is the maximum.

## Sufficient Conditions for a Local Maximum

If the first and second order necessary conditions hold at  $\bar{q}$  and the level sets are closed loops around  $\bar{q}$ , then the function  $f(q)$  has a local maximum at  $\bar{q}$ .

## Sufficient Conditions for a Global Maximum

If the first and second order necessary conditions hold at  $\bar{q}$  and the level sets are closed loops around  $\bar{q}$  and the FOC hold only at  $\bar{q}$ , then this is the global maximizer.

# Non-Negativity Constraints

Many economic variables cannot be negative. Suppose this is true for all variables

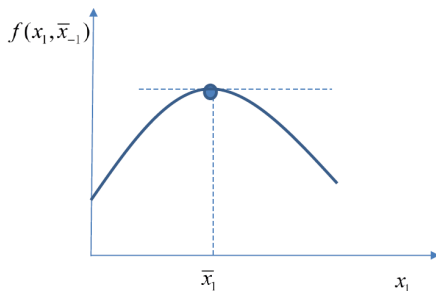
Let  $\bar{x} = (\bar{x}_1, \dots, \bar{x}_n)$  solve  $\max_{x \geq 0} \{f(x)\}$ .

We will consider the first variable. It is helpful to write the optimal value of all the other variables as  $\bar{x}_{-1}$ . Then:

$$\bar{x}_1 \text{ solves } \max_{x_1 \geq 0} f(x_1, \bar{x}_{-1}).$$

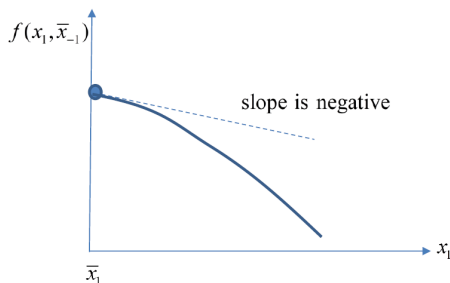
## Case I: $\bar{x}_1 > 0$

For  $x_1$  to be the maximizer, the slope of  $f(x_1, \bar{x}_{-1})$  must be zero at  $x_1$ .



## Case II: $\bar{x}_1 = 0$

For  $\bar{x}_1$  to be the maximizer, the slope of  $f(x_1, \bar{x}_{-1})$  cannot be strictly positive at  $\bar{x}_1$ .



**Necessary condition** can be written as:

$$\frac{\partial f}{\partial x_1}(\bar{x}) \leq 0, \text{ with equality if } \bar{x}_1 > 0$$

## Section 2

# Constrained Maximization

# Constrained Maximization - An Economic Approach

Problem:

$$\max_{x \geq 0} f(x) \text{ subject to } g(x) \leq b$$

Let  $\bar{x}$  be the solution to this problem.

Interpretation, if the firm chooses  $x$  it requires  $g(x)$  units of a resource that is fixed in supply (i.e. floor space of plant, highly skilled workers)

**Assumption 1:** No solution,  $x^* = \arg \max_{x \geq 0} f(x)$  satisfies the resource constraint. Therefore, at  $\bar{x}$ , this constraint is binding.

We interpret  $f(x)$  as the profit of the firm.

# Shadow Price

To solve this problem, we consider the **relaxed problem** in which the firm can purchase additional units at the price  $\lambda$ . Since this is a hypothetical opportunity cost, economists refer to the price as the **shadow price** of the resource rather than a market price.

Suppose that the firm purchases  $g(x) - b$  additional units. Its profit is then:

$$\text{Lagrangian : } \mathcal{L} = f(x) - \lambda(g(x) - b) = f(x) + \lambda(b - g(x))$$

The relaxed problem is then:

$$\max_{x \geq 0} \mathcal{L} = f(x) + \lambda(b - g(x))$$



## Shadow Price Cont.

Suppose that  $\bar{x}$  solves the optimization problem. The net gain to increase  $x_j$  is:

$$\frac{\partial f}{\partial x_j}(\bar{x}) - \lambda \frac{\partial g}{\partial x_j}(\bar{x})$$

- If the net gain is strictly positive, the firm gains by increasing  $x_j$ . Thus:

$$\frac{\partial f}{\partial x_j}(\bar{x}) - \lambda \frac{\partial g}{\partial x_j}(\bar{x}) \leq 0$$

- If the net gain is strictly negative, the firm gains by reducing  $x_j$ . Thus:

$$\frac{\partial f}{\partial x_j}(\bar{x}) - \lambda \frac{\partial g}{\partial x_j}(\bar{x}) \geq 0 \text{ when } \bar{x}_j > 0$$

Thus the marginal net gain is zero at the optimum unless the optimum is zero.

# Constraint Qualification

## Constraint Qualification

Define  $X$  to be the set of feasible vectors; that is:

$$X = \{x \mid x \geq 0 \text{ and } h_i(x) \geq 0, i = 1, \dots, m\}$$

The constraint qualification is said to hold at  $\bar{x} \in X$  if:

- i. For binding constraints at  $\bar{x}$ , the associated gradient vector  $\frac{\partial h_i}{\partial x}(\bar{x}) \neq 0$ ,
- ii.  $\bar{X}$ , the set of non-negative vectors satisfying the linearized binding constraints, has a non-empty interior.

# Kuhn-Tucker Conditions

## Kuhn-Tucker Conditions (First Order Conditions)

Suppose  $\bar{x}$  solves the following problem

$$\max_x \{f(x) | x \in X\} \text{ where } X = \{x | x \geq 0, h_i(x) \geq 0, i = 1, \dots, m\}$$

If Constraint Qualification holds at  $\bar{x}$ , then there exists a vector of shadow prices  $\lambda \geq 0$  such that:

$$\frac{\partial \mathcal{L}}{\partial x_j}(\bar{x}, \lambda) \leq 0, j = 1, \dots, n \text{ with equality if } \bar{x}_j > 0$$

and

$$\frac{\partial \mathcal{L}}{\partial \lambda}(\bar{x}, \lambda) \geq 0, i = 1, \dots, m \text{ with equality if } \lambda_i > 0$$

# Necessary and Sufficient Conditions

## Necessary and Sufficient Conditions for a Maximum

If  $f$  and  $h_i, i = 1, \dots, m$  are all quasi-concave, the Kuhn-Tucker conditions hold at  $\bar{x}$  and for each binding constraint,  $\frac{\partial h_i}{\partial x}(\bar{x}) \neq 0$ , then  $\bar{x}$  solves

$$\max_x \{f(x) \mid x \geq 0, h_i(x) \geq 0, i = 1, \dots, m\}.$$

# Concave Function

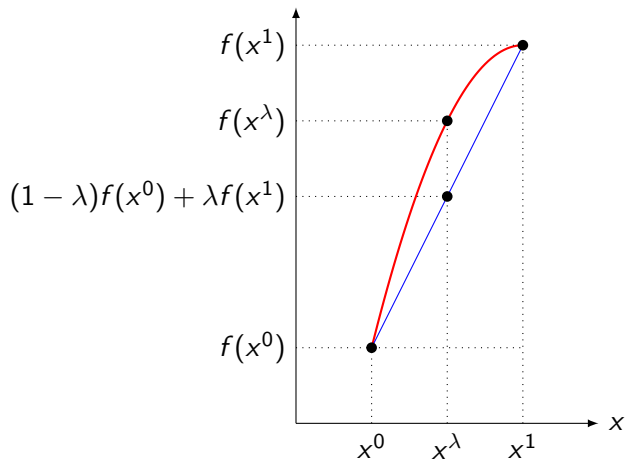
## Definition: Concave and Strictly Concave Function

A function  $f$  is concave on the interval  $[a, b]$  if, for any two points  $x^0$  and  $x^1$  in this interval, and any convex combination  $x^\lambda = (1 - \lambda)x^0 + \lambda x^1$ ,  $0 < \lambda < 1$ ,

$$f(x^\lambda) \geq (1 - \lambda)f(x^0) + \lambda f(x^1)$$

The function is strictly concave if the inequality is always strict.

# Concave Function - Example

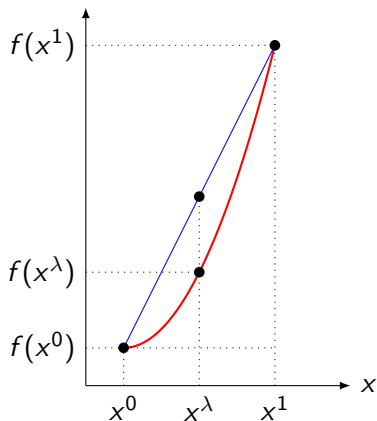


# Quasi-Concave Function

## Definition: Quasi-Concave Function

A function  $f$  is quasi-concave over the interval  $[a, b]$  if, for any two points  $x^0$  and  $x^1$  in this interval such that  $f(x^1) \geq f(x^0)$ ,  $f(x^\lambda) \geq f(x^0)$  where  $x^\lambda = (1 - \lambda)x^0 + \lambda x^1$  and  $\lambda \in (0, 1)$ .

# Quasi-Concave Function - Example





## Example

$$\max_x \{f(x) = \ln(1 + x_1) + \ln(1 + x_2) \mid x \geq 0, h(x) = 2 - x_1 - x_2 \geq 0\}$$

The Lagrangian for the problem is:

$$\mathcal{L}(x, \lambda) = \ln(1 + x_1) + \ln(1 + x_2) + \lambda(2 - x_1 - x_2)$$

The FOC are as follows:

$$\frac{\partial \mathcal{L}}{\partial x_1} = \frac{1}{1 + x_1} - \lambda = 0,$$

$$\frac{\partial \mathcal{L}}{\partial x_2} = \frac{1}{1 + x_2} - \lambda = 0,$$

$$\frac{\partial \mathcal{L}}{\partial \lambda} = 2 - x_1 - x_2 = 0.$$

From the first two conditions  $\bar{x}_1 = \bar{x}_2$ . Substituting into the constraint,  $\bar{x} = (1, 1)$ .

## Section 3

# Envelope Theorem

# Effect of Parameter Change on Maximized Value

Consider a multiproduct price taker firm who has a cost function  $C(q)$ .

Maximized profit is  $\Pi(p) = \max_q \{p \cdot q - C(q)\}$ . Suppose that for any  $p$  there is a unique  $q^*(p)$ .

With data only on profit and prices and outputs, what can be said about the elasticity of profit with respect to the price of commodity  $j$ ?

$$\epsilon(\Pi, p_j) = \frac{\partial \Pi}{\partial p_j} \frac{p_j}{\Pi}$$

## Example, $\epsilon = ?$

$$p^0 = 100, C(q) = q^2$$

Profit,  $pq - q^2$  is maximized at  $q^*(p) = \frac{1}{2}p = 50$  and so  $\Pi^0 = 2500$ .

**Simplistic answer:** Assume that the firm doesn't change its output.

$$\frac{\partial \Pi}{\partial p} = q^*(p^0) = 50 \rightarrow \epsilon(\Pi, p) = \frac{\partial \Pi}{\partial p} \frac{p}{\Pi} = 50 \times \frac{100}{2500} = 2$$

**Sophisticated response:** Take into account the effect of output change.

$$\Pi(p) = pq^*(p) - C(q^*) = pq^*(p) - q^{*2} = p\left(\frac{1}{2}p\right) - \left(\frac{1}{2}p\right)^2 = \frac{1}{4}p^2$$

$$\rightarrow \frac{\partial \Pi}{\partial p}(p) = \frac{1}{2}p \text{ and } \epsilon(\Pi, p) = \frac{\partial \Pi}{\partial p} \frac{p}{\Pi} = \frac{1}{2}p \frac{p}{\frac{1}{4}p^2} = 50 \times \frac{100}{2500} = 2$$

Same answer! What is going on here?

# Envelope Theorem

## Envelope Theorem

Define  $F(\alpha) = f(x^*(\alpha), \alpha)$  where  $x^*(\alpha) = \arg \max_x \{f(x, \alpha) | x \in X \subset \mathbb{R}^n\}$  and  $f \in \mathbb{C}^1$ .

If  $x^*(\alpha)$  is a continuous function then:

$$\frac{dF}{d\alpha} = \frac{\partial f}{\partial \alpha}(x^*(\alpha), \alpha)$$